

# HEIDENHAIN



Product Information

### **ERO 2000 Series**

Angle Encoders without Integral Bearing

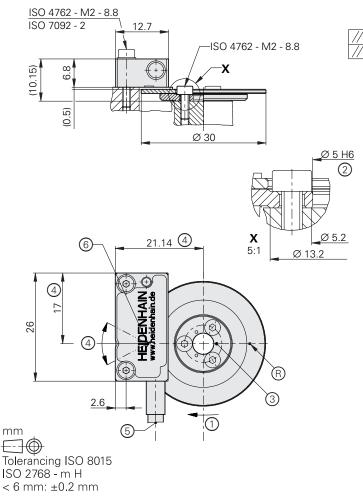
### ERO 2000 series

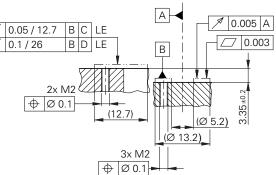
- High resolution and accuracy
- · Low mass and low mass moment of inertia
- Consisting of AK scanning head and TKN circular scale

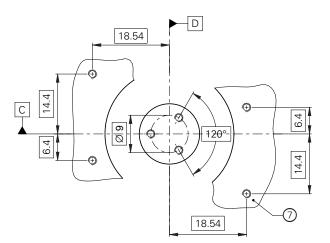


#### Graduation carrier Ø 30 mm

#### **Required mating dimensions**







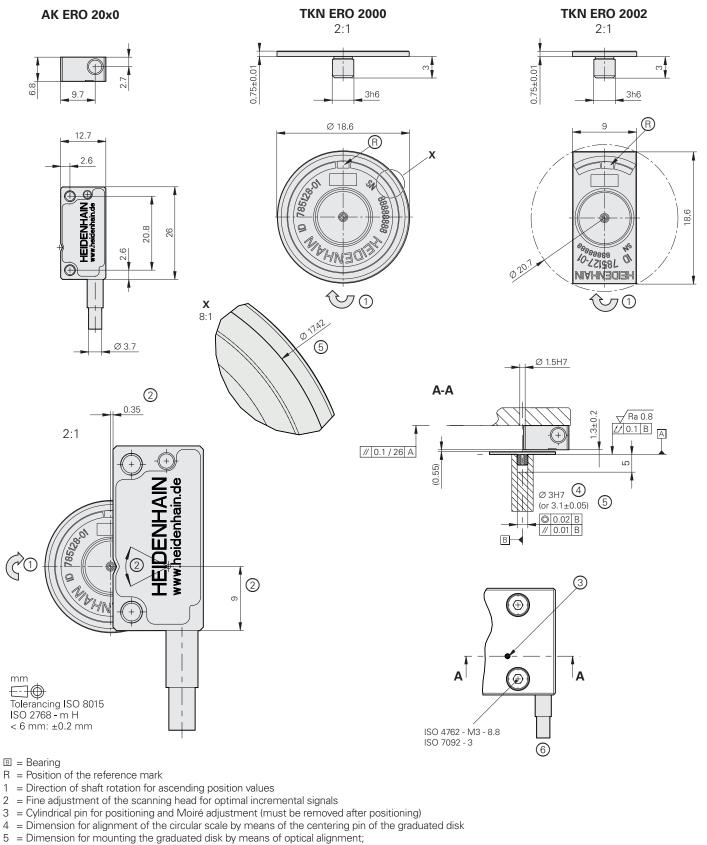
- = Bearing
- (B) = Reference mark1 = Positive direction of rotation
- 2 = Centering collar
- 2 = Centering collar
- 3 = Marks for circular scale centering (3x 120°)
- 4 = Fine adjustment of the scanning head for obtaining optimal incremental signals
- 5 = Alternative cable outlet and connector are available
- 6 = Optical center point
- 7 = For centering of circular scale with two scanning heads

LE = Line element (ISO 1101: 2008)





Graduation carrier 18.6 mm x 9 mm



- do not use the outer glass edge of the graduated disk
- 6 = Alternative cable outlet and connector are available

## Specifications

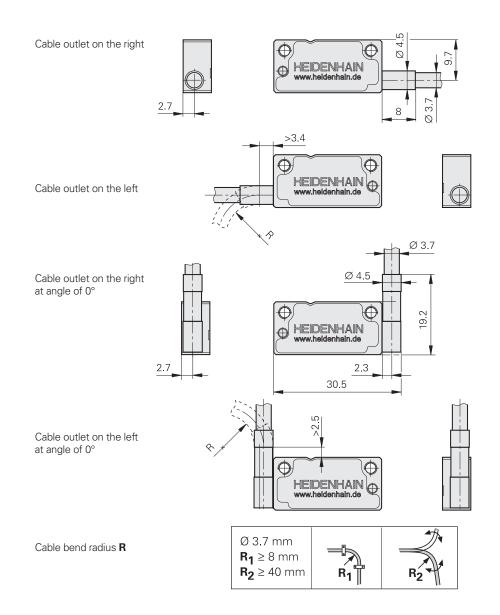
Scanning head	AK ERO 2080					
Interface	$\sim$ 1 V <sub>PP</sub>					
Reference mark signal	Square-wave pulse					
Cutoff frequency –3 dB <sup>1)</sup>	≥ 1 MHz					
Electrical connection*	15-pin D-sub connector (male) with 0.5 m/1 m/1.5 m/3 m cable 12-pin SHR-12V-S connector (female) with 0.5 m/1 m/1.5 m/3 m cable Cable outlet on the left or right and straight or angled					
Cable length	With HEIDENHAIN cable: $\leq$ 20 m; during signal adjustment with the PWM 21: $\leq$ 3 m					
Supply voltage	DC 5V ±0.5V					
Current consumption	≤ 150 mA (without load)					
Vibration 55 Hz to 2000 Hz Shock 6 ms	$\leq 500 \text{ m/s}^2 \text{ (EN 60068-2-6)}$ $\leq 1000 \text{ m/s}^2 \text{ (EN 60068-2-27)}$					
Operating temperature	-10 °C to 70 °C					
Protection	IP50					
Mass Scanning head Connector Cable	$\approx$ 5 g (without cable) $\approx$ 71 g $\approx$ 22 g/m					

\* Please select when ordering <sup>1)</sup> Maximum frequency during referencing: 500 kHz

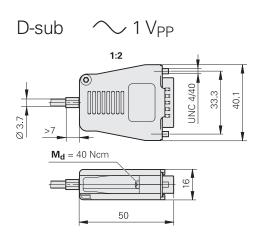
Circular scale	TKN ERO 2000 (full cire	cle)	TKN ERO 2002 <sup>3)</sup> (segment)					
Measuring standard	SUPRADUR graduation on glass							
Measuring range	360°		45°					
Signal periods	4096	2500 <sup>3)</sup>	2500 over 360°					
Accuracy of graduation <sup>1)</sup>	±8″	±10"	_					
Interpolation error <sup>2)</sup>	±0.3"	±0.5"	±0.5"					
Position noise RMS (1 MHz)	0.03"	0.04"	0.04"					
Reference marks	One		One	One on every side				
Hub inside diameter	5 mm	-	-					
Dimensions of graduation carrier	Ø 30 mm	Ø 18.6 mm	18.6 mm x 9 mm					
Centering pin	-	3 mm	3 mm					
Mech. permissible shaft speed	≤ 14000 rpm							
Moment of inertia	4.1 · 10 <sup>-7</sup> kgm <sup>2</sup>	$2.2 \cdot 10^{-8} \text{ kgm}^2$	$1.1 \cdot 10^{-8} \text{ kgm}^2$					
Protection EN 60529	Complete, mounted encoder: IP00							
Mass	≈ 5.2 g	≈ 0.56 g	≈ 0.36 g					

 <sup>1)</sup> When centered with two scanning heads
<sup>2)</sup> The position error within one signal period and the graduation accuracy together yield the encoder-specific error; for additional mounting and bearing errors of the measured shaft, see *Measuring accuracy* in the *Modular Angle Encoders With Optical Scanning* <sup>3)</sup> Available as a prototype; orderable only after consultation

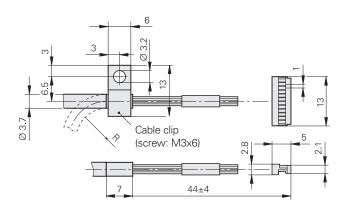
### **Cable outlets**



### Connectors



SHR-12V-S  $\sim$  1 V<sub>PP</sub>



### **Electrical connection**

Pin layout													
15-pin D-sub connector (male)							12-pin SHR-12V-S connector (female)						
	Power supply				Incremental signals				Other signals				
	4	12	2	10	1	9	3	11	14	7	13	15	5/6/8
Е	1	-	2	-	3	4	6	5	8	7	9	11	12/10
$\sim$ 1 V <sub>PP</sub>	U <sub>P</sub>	Sensor U <sub>P</sub>	0 V •	Sensor 0 ∨	A+	<b>A</b> –	B+	В-	R+	R–	Vacant <sup>1)</sup>	Vacant <sup>1)</sup>	Vacant
	Brown/ Green	/	White/ Green	/	Brown	Green	Gray	Pink	Red	Black	Violet	Yellow	/

**Shield** on housing;  $U_P$  = Power supply voltage

Sensor: The sense line is connected in the connector with the corresponding power line.

Vacant pins or wires must not be used. <sup>1)</sup> Required for signal adjustment with the PWM 21

#### Adapter cables and connecting cables

<b>PUR</b> 6 x (2 x 0.19 mm <sup>2</sup> ); $A_P = 2 \times 0.19 \text{ mm}^2$								
<b>PUR</b> 4 x (2 x 0.16 mm <sup>2</sup> ) + (4 x 0.5 mm <sup>2</sup> ); $A_P = 2 \times 0.5 \text{ mm}^2$		Ø8mm	Ø 6 mm <sup>1)</sup>					
<b>Adapter cable</b> with 15-pin D-sub connector (female) and 12-pin M23 connector (male)		331693-xx	355215-xx					
<b>Adapter cable</b> with 15-pin D-sub connector (female) and 15-pin D-sub connector (male)		335074-xx	355186-xx					
<b>Connecting cable</b> with 15-pin D-sub connector (female) and stripped cable end		332433-xx	355209-xx					
<b>Connecting cable</b> with 15-pin D-sub connector (female) and 15-pin D-sub connector (female) with pin layout for the IK 220		335077-xx	349687-xx					
<b>Signal cable</b> with stripped cable ends (15-pin) <sup>2)</sup>		816317-xx	816323-xx					

<sup>1)</sup> Cable length for  $\emptyset$  6 mm: max. 9 m

<sup>2)</sup> Cable design:  $4 \times (2 \times 0.14 \text{ mm}^2) + (4 \times 0.5 \text{ mm}^2)$ 

A<sub>P</sub>: Cross section of supply lines

#### Accessory

Adapter connector from SHR-12V-S to D-sub for signal adjustment with the PWM 21 ID 1234385-01

HEIDENHAIN

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This Product Information document supersedes all previous editions, which thereby become invalid. The basis for ordering from HEIDENHAIN is always the Product Information document edition valid when the order is made.

### (D) Further information:

Comply with the requirements described in the following documents to ensure the correct and intended operation of the encoder:

- Brochure: Modular Angle Encoders With Optical Scanning
- Brochure: Interfaces of HEIDENHAIN Encoders
- Brochure: Cables and Connectors

1222041-xx 1078628-xx 1206103-xx